

Section 6.5

(1)(a)  $J_{rs}$  is a  $n \times n$  matrix whose  $rs$ -component is 1, where  $1 \leq r, s \leq n$  and  $r \neq s$ , and all other components are 0. In other words,  $J_{rs}$  is a matrix with a one in a non-diagonal entry and 0 everywhere else.

If  $E_{rs} = I + J_{rs}$ , then  $E_{rs}$  is a matrix with a one in its diagonal and in another, non-diagonal entry. From theory we know that column operations do not change  $|D(E_{rs})|$ . Take the  $(-1)r$  col of  $E_{rs}$  and add it to the  $s$  col of  $E_{rs}$ . You obtain  $I$  back. But, by previous work  $\text{DET}(I) = 1 = D(E_{rs})$ . We did not swap two columns, so the sign remains the same.

(1)(b) A  $n \times n$  matrix. the effect of multiplying  $E_{rs}A$  is to obtain the matrix  $A$  such that the the row  $s$  of  $A$  is added to the row  $r$ . Similarly, the product  $AE_{rs}$  results in matrix  $A$  such that the col  $r$  of  $A$  is added to the col  $s$ .

(2) If  $A$  is a triangular matrix, (square), then its columns look like:

$$A^1 = \begin{bmatrix} w_{11} \\ 0 \\ \vdots \\ 0 \end{bmatrix}, A^2 = \begin{bmatrix} w_{12} \\ w_{22} \\ \vdots \\ 0 \end{bmatrix}, \dots, A^n = \begin{bmatrix} w_{1n} \\ w_{2n} \\ \vdots \\ w_{nn} \end{bmatrix} \quad \text{this is upper triangular, but the reasoning is pretty much the same}$$

for lower triangular also.

We want to prove that the  $A^i$  are L.I iff  $w_{ii} \neq 0 \quad \forall i: 1 \leq i \leq n$ .

( $\Leftarrow$ ) we can reduce this problem to solving:

$$\begin{aligned} c_1 w_{11} &= 0 \\ c_1 w_{12} + c_2 w_{22} &= 0 \\ &\vdots \\ c_1 w_{1n} + c_2 w_{2n} + \dots + c_n w_{nn} &= 0 \end{aligned}$$

By hypothesis  $w_{ii} \neq 0$ , hence:  
 $\left\{ \begin{array}{l} * \\ \Rightarrow \end{array} \right. c_i = 0 \quad \forall i \Rightarrow A^i \text{ are L.I.}$   
 we simply substitute equation by equation.

$$c_1 w_{1n} + c_2 w_{2n} + \dots + c_n w_{nn} = 0$$

( $\Rightarrow$ ) Suppose  $\exists i$  such that  $w_{ii} = 0$  and that  $A^i$ 's are L.I.  
 then we can see from  $*$  that  $A$  will have a non trivial solution  
 Hence  $\dim(\text{Ker}(A)) > 0$ . But  $n = \dim(\text{Ker}(A)) + \dim(\text{Im}(A))$  and  
 $A^i$ 's are L.I and there are  $n$  of them. Thus,  $\{A^1, \dots, A^n\}$  form  
 a basis.  $\Rightarrow \dim(\text{Im}(A)) = n$ , which contradicts the fact that  
 $\dim(\text{Ker}(A)) > 0$ . therefore, it must be the case that  $w_{ii} \neq 0 \quad \forall i$ .

## Additional Exercises

(2) (a) Let  $B: \mathbb{K}^n \times \mathbb{K}^n \rightarrow \mathbb{K}$  be a bilinear form, such that  $B(v, v) = 0 \forall v \in V$ . Show that  $B(v, w) = -B(w, v) \forall v, w \in V$ .

By hypothesis  $0 = B(v+w, v+w)$

By linearity  $B(v+w, v+w) = B(v, v) + B(v, w) + B(w, v) + B(w, w)$

By hypothesis both  $B(v, v) = 0$  and  $B(w, w) = 0$ . Hence,

$$0 = B(v, w) + B(w, v) \Rightarrow B(v, w) = -B(w, v).$$

(b) Let  $F: (\mathbb{K}^n)^n \rightarrow \mathbb{K}$  be a multilinear form so that if  $v_i = v_j$  with  $i \neq j$ , then  $F(v_1, \dots, v_n) = 0$ . Show that  $F$  is alternating.

Solution:  $F$  is alternating means  $F(v_1, \dots, v_j, v_{j+1}, \dots, v_n) = -F(v_1, \dots, v_{j+1}, v_j, \dots, v_n)$ .

$F(v_1, \dots, v_j + v_{j+1}, v_{j+1}, \dots, v_n) =$  By linearity.

$F(v_1, \dots, v_j, v_{j+1}, \dots, v_n) + F(v_1, \dots, v_{j+1}, v_{j+1}, \dots, v_n)$

But, by hypothesis,  $F(v_1, \dots, v_{j+1}, v_{j+1}, \dots, v_n) = 0$ .

Also,

$F(v_1, \dots, v_j, v_j + v_{j+1}, \dots, v_n) =$  By linearity

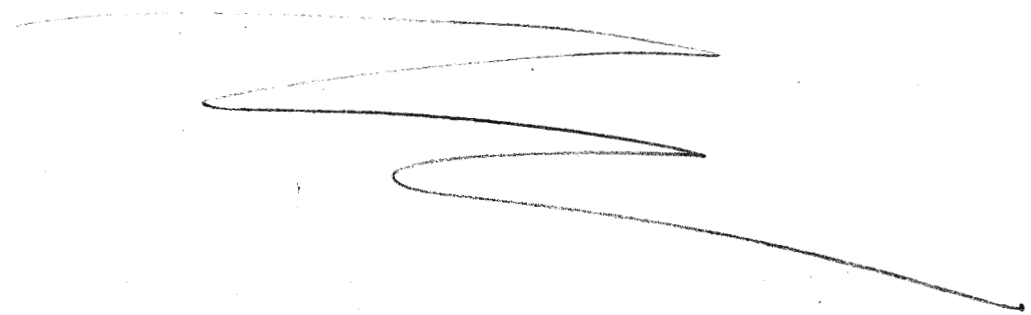
$F(v_1, \dots, v_j, v_j, \dots, v_n) + F(v_1, \dots, v_j, v_{j+1}, \dots, v_n)$

But, by hypothesis,  $F(v_1, \dots, v_j, v_j, \dots, v_n) = 0$

Hence,  $F(v_1, \dots, v_j, v_{j+1}, \dots, v_n) = -F(v_1, \dots, v_{j+1}, v_j, \dots, v_n)$

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the additional exercise (corrected) on permutation  
is on the last page.



Section 8.1

(1) Let  $a \in \mathbb{K}$  and  $a \neq 0$ . Prove that the eigenvectors of the matrix

$$\begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix} = A$$

generate a 1-dimensional space, and give a basis for this space

Solution: An eigenvector  $v$  is such that:  $Av = \lambda v$ , where  $\lambda \in \mathbb{K}$ .

$$\Rightarrow \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} \lambda v_1 \\ \lambda v_2 \end{pmatrix} \Rightarrow \begin{matrix} v_1 + av_2 = \lambda v_1 \\ v_2 = \lambda v_2 \end{matrix} \Rightarrow \lambda = 1 \text{ or } v_2 = 0$$

If  $v_2 = 0 \Rightarrow v_1 = \lambda v_1 \Rightarrow \lambda = 1$ . Hence,  $\lambda = 1$  always.

$$v_1 + av_2 = v_1 \Rightarrow av_2 = 0, \text{ but } a \neq 0, \text{ hence } v_2 = 0$$

the eigenvectors belong to the space generated by  $\langle \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle$ .

(3) Let  $A$  be a diagonal matrix with diagonal elements  $a_{11}, \dots, a_{nn}$ . What is the dimension of the space generated by the eigenvectors of  $A$ ? Exhibit a basis for the space, and give the eigen values.

Solution:

$$Av = \lambda v \Rightarrow \begin{bmatrix} a_{11} & 0 & \dots & 0 \\ 0 & a_{22} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \lambda \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$\Rightarrow \begin{matrix} a_{11}v_1 = \lambda v_1 \\ a_{22}v_2 = \lambda v_2 \end{matrix}$$

$$w_1 = e_1 \quad \lambda_1 = a_{11}$$

$$w_2 = e_2 \quad \lambda_2 = a_{22}$$

$$a_{nn}v_n = \lambda v_n$$

$$w_n = e_n \quad \lambda_n = a_{nn}$$

the dimension is  $n$ .

the basis is  $\{e_1, \dots, e_n\}$ .

the eigen values are

the diagonal elements,

i.e., each  $e_i$  have eigen value  $a_{ii}$ .

(4) Let  $A = (a_{ij})$  be an  $n \times n$  matrix such that for each  $i = 1, \dots, n$  we have  $\sum_{j=1}^n a_{ij} = 0$ . Show that 0 is an eigen value of  $A$ .

Solution:  $A$  is such that the sum of the element in each row is zero

0 is an eigen value of  $A$  iff,  $Av = 0v$ , i.e.,

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} a_{11}v_1 + a_{12}v_2 + \dots + a_{1n}v_n \\ a_{21}v_1 + a_{22}v_2 + \dots + a_{2n}v_n \\ \vdots \\ a_{n1}v_1 + a_{n2}v_2 + \dots + a_{nn}v_n \end{bmatrix}, \text{ if we take } \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$\text{then } A \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} a_{11} + a_{12} + \dots + a_{1n} \\ a_{21} + a_{22} + \dots + a_{2n} \\ \vdots \\ a_{n1} + a_{n2} + \dots + a_{nn} \end{bmatrix} = \text{By hypothesis} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = 0 \cdot \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \text{ Hence,}$$

$\begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$  is eigenvector with eigen value 0.

(5) (a) Show that if  $\theta \in \mathbb{R}$ , then the matrix

$$A = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$

always has an eigen vector in  $\mathbb{R}^2$ , and in fact that there exists a vector  $v_1$  such that  $Av_1 = v_1$ .

Solution:  $Av = \lambda v \Rightarrow \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

$$\Rightarrow \begin{cases} \cos \theta x_1 + \sin \theta x_2 = \lambda x_1 \\ \sin \theta x_1 - \cos \theta x_2 = \lambda x_2 \end{cases} \quad (*) \quad \Rightarrow \text{where } \underline{\cos \theta \neq 1}$$

Using the hint, let  $x_1 = \frac{\sin \theta}{1 - \cos \theta}$  and  $x_2 = x_2$ . Replacing into (\*):

let  $\lambda = 1$ : 
$$\begin{cases} \cos \theta \left( \frac{\sin \theta}{1 - \cos \theta} \right) + \sin \theta x_2 = \frac{\sin \theta}{1 - \cos \theta} & (1) \\ \sin \theta \left( \frac{\sin \theta}{1 - \cos \theta} \right) - \cos \theta x_2 = x_2 & (2) \end{cases}$$

From (2): 
$$\frac{\sin^2 \theta}{1 - \cos \theta} = x_2 + \cos \theta x_2 = x_2 (1 + \cos \theta)$$

$$\Rightarrow \frac{\sin^2 \theta}{(1 - \cos \theta)(1 + \cos \theta)} = x_2 = \frac{\sin^2 \theta}{1 + \cos \theta - \cos \theta - \cos^2 \theta} = \frac{\sin^2 \theta}{1 - \cos^2 \theta} = \frac{\sin^2 \theta}{\sin^2 \theta} = 1$$

Hence,  $x_2 = 1$ . One can verify that  $x = \begin{pmatrix} \frac{\sin \theta}{1 - \cos \theta} \\ 1 \end{pmatrix}$  is an eigenvector of  $A$  with eigenvalue 1, i.e.,  $Ax = x$  (if  $\cos \theta \neq 1$ ).

$$\begin{aligned} Ax &= \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} \frac{\sin \theta}{1 - \cos \theta} \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{\cos \theta \sin \theta}{1 - \cos \theta} + \sin \theta \\ \frac{\sin^2 \theta}{1 - \cos \theta} - \cos \theta \end{pmatrix} = \begin{pmatrix} \frac{\cos \theta \sin \theta + \sin \theta - \cos \theta \sin \theta}{1 - \cos \theta} \\ \frac{\sin^2 \theta - \cos \theta + \cos^2 \theta}{1 - \cos \theta} \end{pmatrix} \\ &= \begin{pmatrix} \frac{\sin \theta}{1 - \cos \theta} \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{\sin \theta}{1 - \cos \theta} \\ 1 \end{pmatrix} = x. \end{aligned}$$

If  $\cos \theta = 1$ , then  $\cos^2 \theta = 1 \Rightarrow \sin^2 \theta = 0 \Rightarrow \sin \theta = 0$ . the matrix

$A$  is now:  $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$  the eigen vector would be:

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} x_1 = \lambda x_1 \Rightarrow \lambda = 1 \Rightarrow x_2 = 0 \\ -x_2 = \lambda x_2 \end{cases}$$

the eigen vectors are  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$ , with eigenvalue 1.

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③

(5) (b) Let  $v_2 \in \mathbb{R}^2$  perpendicular to  $v_1 = \begin{pmatrix} \frac{\sin \theta}{1 - \cos \theta} \\ 1 \end{pmatrix}$ . Show that  $A v_2 = -v_2$ . Define this to mean that  $A$  is a reflection.

Solution:  $v_1 \cdot v_2 = 0 \Leftrightarrow \left( \frac{\sin \theta}{1 - \cos \theta}, 1 \right) \cdot (v_{z1}, v_{z2}) = 0$

$$\Leftrightarrow \frac{\sin \theta}{1 - \cos \theta} v_{z1} + v_{z2} = 0$$

If  $\cos \theta \neq 1$ , then  $(v_{z1}, v_{z2}) = (1 - \cos \theta, -\sin \theta)$  is a vector perpendicular to  $v_1$ , i.e.,  $\frac{\sin \theta}{1 - \cos \theta} (1 - \cos \theta) - \sin \theta = \sin \theta - \sin \theta = 0$ .

TAKE  $A \cdot v_2 = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} 1 - \cos \theta \\ -\sin \theta \end{pmatrix} = \begin{pmatrix} \cos \theta (1 - \cos \theta) - \sin^2 \theta \\ \sin \theta (1 - \cos \theta) + \cos \theta \sin \theta \end{pmatrix} = \begin{pmatrix} \cos \theta - (\cos^2 \theta + \sin^2 \theta) \\ \sin \theta - \sin \theta \cos \theta + \sin \theta \cos \theta \end{pmatrix}$   
 $= \begin{pmatrix} -1 + \cos \theta \\ \sin \theta \end{pmatrix} = -1 \begin{pmatrix} 1 - \cos \theta \\ -\sin \theta \end{pmatrix} = -v_2$ .

If  $\cos \theta = 1$ , then  $(v_{z1}, v_{z2}) = (0, 1)$ , hence,

$$A v_2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} = - \begin{pmatrix} 0 \\ 1 \end{pmatrix} = -v_2$$

$A$  reflects  $v$  in the line perpendicular to it.

(6) Let  $R(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$  be the matrix of rotation.

Show that  $R(\theta)$  does not have any real eigenvalues.

Solution: To find the real eigenvalues  $\lambda$  we need to solve:

$$\det(R(\theta) - \lambda I) = 0 \Leftrightarrow \det \left( \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} - \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} \right) = 0$$

$$\Leftrightarrow \det \begin{pmatrix} \cos \theta - \lambda & -\sin \theta \\ \sin \theta & \cos \theta - \lambda \end{pmatrix} = 0 \Leftrightarrow (\cos \theta - \lambda)^2 + \sin^2 \theta = 0 \Leftrightarrow$$

$$\cos^2 \theta - 2 \cos \theta \lambda + \lambda^2 + \sin^2 \theta = 0 \Leftrightarrow \lambda^2 - 2 \cos \theta \lambda + 1 = 0$$

We attempt to solve this quadratic equation:

$$\frac{2 \cos \theta \pm \sqrt{4 \cos^2 \theta - 4}}{2} \Rightarrow \text{the discriminant} = 4(\cos^2 \theta - 1)$$

Hence, if  $\cos^2 \theta < 1 \Rightarrow 4(\cos^2 \theta - 1) < 0 \Rightarrow$  negative discriminant, no real solution.

If  $\cos^2 \theta = 1 \Rightarrow 4(1 - 1) = 0 \Rightarrow$  there is a real solution if  $\cos^2 \theta = 1$

But, if  $\cos^2 \theta = 1$  then  $\sin^2 \theta = 0 \Rightarrow \cos \theta = \pm 1$  and  $\sin \theta = 0$   
 $\Rightarrow R = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  or  $R = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$ , i.e.,  $R = \pm I$ .

(7) Let  $V$  be a f.d. v.s. Let  $A: V \rightarrow V$  and  $B: V \rightarrow V$  be both linear. Assume  $AB = BA$ . Show that if  $v$  is an eigenvector of  $A$ , with eigenvalue  $\lambda$ , then  $Bv$  is an eigenvector of  $A$ , with eigenvalue  $\lambda$  also if  $Bv \neq 0$ .

Solution: By definition,  $v$  is an eigenvector of  $A$  with eigenvalue  $\lambda$  iff  $Av = \lambda v$ . Here we can apply  $B$  to both sides:

$B(Av) = B(\lambda v)$ .  $B$  is a linear map, thus the scalar  $\lambda$  comes out:

$B(Av) = \lambda(Bv)$ . By composition of linear maps

$(BA)v = \lambda(Bv)$ . By hypothesis  $BA = AB$

$(AB)v = \lambda(Bv)$ . By composition of linear maps

$A(Bv) = \lambda(Bv)$ . By definition of eigenvector,  $Bv$  is an eigenvector of  $A$  with eigenvalue  $\lambda$ . ( $Bv \neq 0$ )

### Section 8.2

(1) Let  $A$  be a diagonal matrix.

(a) what is the characteristic polynomial of  $A$ ?

$$P_A(t) = \text{Det}(A - tI) = \text{Det} \begin{pmatrix} a_1 - t & 0 & \dots & 0 \\ 0 & a_2 - t & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & a_n - t \end{pmatrix} \text{ by previous work we know}$$

that the determinant of a diagonal matrix is the product of its diagonal entries, hence  $P_A(t) = (a_1 - t)(a_2 - t) \dots (a_n - t)$

(b) what are its eigen values?

An eigenvalue is such that  $P_A(t) = 0 \Rightarrow (a_1 - t)(a_2 - t) \dots (a_n - t) = 0$   
the eigenvalues are  $a_1, \dots, a_n$ , the diagonal entries.

(2) Let  $A$  be a lower-triangular matrix, what is the characteristic polynomial of  $A$ , and what are its eigenvalues?

Same as before:  $P_A(t) = \text{Det}(A - tI) = \text{Det} \begin{pmatrix} a_{11} - t & 0 & \dots & 0 \\ a_{21} & a_{22} - t & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$  by previous work:

$P_A(t) = (a_{11} - t)(a_{22} - t) \dots (a_{nn} - t)$ . Eigen values are  $a_{11}, a_{22}, \dots, a_{nn}$ .

(5) Find the eigenvalues and eigenvectors of the following matrices. Show that the eigen vectors form a 1-dimensional space.

(a)  $\begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix} = A$ .  $P_A(t) = \det(A - tI) = \det\left(\begin{pmatrix} 2-t & -1 \\ 1 & -t \end{pmatrix}\right) = (2-t)(-t) + 1 = t^2 - 2t + 1$ .

the eigenvalue  $t$  is such that  $P_A(t) = 0 \Leftrightarrow t^2 - 2t + 1 = 0$

$\Leftrightarrow (t-1)^2 = 0 \Rightarrow \boxed{t=1}$  with multiplicity two.

eigenvalue +1:

$\begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} 2x_1 - x_2 = x_1 \Rightarrow 2x_2 - x_2 = x_1 \Rightarrow x_2 = x_1 \\ x_1 = x_2 \end{cases}$

$V_{+1} = \left\{ \begin{pmatrix} x_1 \\ x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\rangle$ , a one-dimensional space.

(b)  $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = A \Rightarrow P_A(t) = \det(A - tI) = \det\left(\begin{pmatrix} 1-t & 1 \\ 0 & 1-t \end{pmatrix}\right) = (1-t)^2$

the eigenvalue  $t$  is such that  $P_A(t) = 0 \Leftrightarrow (1-t)^2 = 0 \Rightarrow t=1$ .

eigenvalue +1:

$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} x_1 + x_2 = x_1 \Rightarrow x_2 = 0 \\ x_2 = x_2 \end{cases}$

$V_{+1} = \left\{ \begin{pmatrix} x_1 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\rangle$ , a one-dimensional space

(c)  $\begin{pmatrix} 2 & 0 \\ 1 & 2 \end{pmatrix} = A \Rightarrow P_A(t) = \det(A - tI) = \det\left(\begin{pmatrix} 2-t & 0 \\ 1 & 2-t \end{pmatrix}\right) = (2-t)^2$

the eigenvalue  $t$  is such that  $P_A(t) = 0 \Leftrightarrow (2-t)^2 = 0 \Rightarrow t=2$ .

eigenvalue +2:

$\begin{pmatrix} 2 & 0 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2x_1 \\ 2x_2 \end{pmatrix} \Rightarrow \begin{cases} 2x_1 = 2x_1 \\ x_1 + 2x_2 = 2x_2 \Rightarrow x_1 = 0 \end{cases}$

$V_{+2} = \left\{ \begin{pmatrix} 0 \\ x_2 \end{pmatrix} \mid x_2 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\rangle$ , a one-dimensional space

we can check this:

$A \cdot v = \begin{pmatrix} 2 & 0 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 2x_2 \end{pmatrix} = 2 \begin{pmatrix} 0 \\ x_2 \end{pmatrix} = 2v$ .

$$(d) \begin{pmatrix} 2 & -3 \\ 1 & -1 \end{pmatrix} = A \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} 2-t & -3 \\ 1 & -1-t \end{pmatrix}$$

$$= (2-t)(-1-t) + 3 = -2 - 2t + t + t^2 + 3 = t^2 - t + 1$$

To find eigenvalues, set  $P_A(t) = 0 \Leftrightarrow t^2 - t + 1 = 0$

Solving the quadratic equation:

$$\frac{1 \pm \sqrt{1-4}}{2} = \frac{1 \pm \sqrt{-3}}{2} = \frac{1 \pm \sqrt{3}i}{2}$$

We have two eigen values:  $\frac{1 + \sqrt{3}i}{2} = \lambda_1$  and  $\frac{1 - \sqrt{3}i}{2} = \lambda_2$

eigenvalue  $\lambda_1$ :

$$\begin{pmatrix} 2 & -3 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \lambda_1 \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} 2x_1 - 3x_2 = \lambda_1 x_1 \\ x_1 - x_2 = \lambda_1 x_2 \end{cases}$$

$$\Rightarrow \begin{cases} 2x_1 - \lambda_1 x_1 = 3x_2 \Rightarrow x_1(2 - \lambda_1) = 3x_2 \\ x_1 = \lambda_1 x_2 + x_2 \Rightarrow x_1 = x_2(1 + \lambda_1) \end{cases}$$

Let  $x_2 = 1$ , then  $\Rightarrow x_1 = (1 + \lambda_1)$ , hence

$$V_{\lambda_1} = \left\{ \begin{pmatrix} 1 + \lambda_1 \\ x_2 \end{pmatrix} \mid x_2 \in \mathbb{C} \right\} = \left\langle \begin{pmatrix} 3 + \sqrt{3}i \\ 2 \\ 1 \end{pmatrix} \right\rangle \quad \text{Both are one-dimensional v.s.}$$

$$V_{\lambda_2} = \left\{ \begin{pmatrix} 1 + \lambda_2 \\ x_2 \end{pmatrix} \mid x_2 \in \mathbb{C} \right\} = \left\langle \begin{pmatrix} 3 - \sqrt{3}i \\ 2 \\ 1 \end{pmatrix} \right\rangle$$

$$(6) (a) A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}, P_A(t) = \det \begin{pmatrix} 1-t & 1 & 1 \\ 0 & 1-t & 1 \\ 0 & 0 & 1-t \end{pmatrix}$$

$$= (1-t) \det \begin{pmatrix} 1-t & 1 \\ 0 & 1-t \end{pmatrix} - 1 \det \begin{pmatrix} 0 & 1 \\ 0 & 1-t \end{pmatrix} + 1 \det \begin{pmatrix} 0 & 1-t \\ 0 & 0 \end{pmatrix} = (1-t)^3$$

$\Rightarrow$  the only eigen value is  $t = 1$ .

eigenvectors for eigen value  $t = 1$ :

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \Rightarrow \begin{aligned} x_1 + x_2 + x_3 &= x_1 \Rightarrow x_1 + x_2 = x_1 \Rightarrow x_2 = 0 \\ x_2 + x_3 &= x_2 \Rightarrow x_3 = 0 \\ x_3 &= x_3 \end{aligned}$$

$$V_1 = \left\{ \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\rangle. \quad \text{we can check:}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} = 1 \cdot \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix}$$



$$8.2.6 (b) \quad A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} 1-t & 1 & 0 \\ 0 & 1-t & 1 \\ 0 & 0 & 1-t \end{pmatrix}$$

$$= (1-t) \det \begin{pmatrix} 1-t & 1 \\ 0 & 1-t \end{pmatrix} - 1 \det \begin{pmatrix} 0 & 1 \\ 0 & 1-t \end{pmatrix} + 0 \cdot \det(\dots) = (1-t)^3.$$

the only eigenvalue is  $t=1$ .

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \Rightarrow \begin{cases} x_1 + x_2 = x_1 \Rightarrow x_2 = 0 \\ x_2 + x_3 = x_2 \Rightarrow x_3 = 0 \\ x_3 = x_3 \end{cases}$$

$V_1 = \left\{ \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\rangle$ , a one dimensional vector space.

8.2.6 (7) (a)

$$A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} -t & 1 & 0 & 0 \\ 0 & -t & 1 & 0 \\ -1 & 0 & -t & 1 \\ 1 & 0 & 0 & -t \end{pmatrix}$$

$$= -t \det \begin{pmatrix} -t & 1 & 0 \\ 0 & -t & 1 \\ 0 & 0 & -t \end{pmatrix} - 1 \det \begin{pmatrix} 0 & 1 & 0 \\ 0 & -t & 1 \\ 1 & 0 & -t \end{pmatrix}$$

$$= (-t)(-t)t^2 - 1(-1) \det \begin{pmatrix} 0 & 1 \\ 1 & -t \end{pmatrix} = \boxed{t^4 - 1}$$

To find eigenvalues, set  $P_A(t) = 0 \Leftrightarrow t^4 - 1 = 0 \Rightarrow \boxed{t = \pm 1}$

eigenvalue +1:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \Rightarrow \begin{cases} x_2 = x_1 \\ x_3 = x_2 \Rightarrow x_1 = x_3 = x_4 = x_2 \\ x_4 = x_3 \\ x_1 = x_4 \end{cases}$$

$V_{+1} = \left\{ \begin{pmatrix} x_1 \\ x_1 \\ x_1 \\ x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle$ , we can check:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_1 \\ x_1 \\ x_1 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_1 \\ x_1 \\ x_1 \end{pmatrix} = 1 \cdot \begin{pmatrix} x_1 \\ x_1 \\ x_1 \\ x_1 \end{pmatrix}.$$

eigenvalue -1:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -x_1 \\ -x_2 \\ -x_3 \\ -x_4 \end{pmatrix} \Rightarrow \begin{cases} x_2 = -x_1 \Rightarrow x_1 = -x_2 = -x_4 = x_3 \\ x_3 = -x_2 \Rightarrow x_3 = -x_4 = -x_2 \\ x_4 = -x_3 \\ x_1 = -x_4 \end{cases}$$

$V_{-1} = \left\{ \begin{pmatrix} x_1 \\ -x_1 \\ x_1 \\ -x_1 \end{pmatrix}, x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} \right\rangle$

8.2.7.

$$(b) A = \begin{pmatrix} -1 & 0 & 1 \\ -1 & 3 & 0 \\ -4 & 13 & -1 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} -1-t & 0 & 1 \\ -1 & 3-t & 0 \\ -4 & 13 & -1-t \end{pmatrix}$$

$$= (-1-t) \det \begin{pmatrix} 3-t & 0 \\ 13 & -1-t \end{pmatrix} + 1 \cdot \det \begin{pmatrix} -1 & 3-t \\ -4 & 13 \end{pmatrix}$$

$$= (-1-t)(3-t)(-1-t) + (-13) - ((-4)(3-t))$$

$$= (-1-t)^2(3-t) - 13 + 12 - 4t = (1+2t+t^2)(3-t) - 1 - 4t$$

$$= 3 + 6t + 3t^2 - t - 2t^2 - t^3 - 1 - 4t = -t^3 + t^2 + t + 2$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow -t^3 + t^2 + t + 2 = 0 \Leftrightarrow t^3 - t^2 - t - 2 = 0$

this polynomial has a unique real root  $t=2$ .

Eigenvectors:

$$\begin{pmatrix} -1 & 0 & 1 \\ -1 & 3 & 0 \\ -4 & 13 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2x_1 \\ 2x_2 \\ 2x_3 \end{pmatrix} \Rightarrow \begin{cases} -x_1 + x_3 = 2x_1 \Rightarrow x_3 = 3x_1 \Rightarrow x_3 = 3x_2 \\ -x_1 + 3x_2 = 2x_2 \Rightarrow -x_1 = -x_2 \Rightarrow x_1 = x_2 \\ -4x_1 + 13x_2 - x_3 = 2x_3 \end{cases}$$

$$V_2 = \left\{ \begin{pmatrix} x_1 \\ x_1 \\ 3x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} \right\rangle. \text{ we can check this:}$$

$$\begin{pmatrix} -1 & 0 & 1 \\ -1 & 3 & 0 \\ -4 & 13 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_1 \\ 3x_1 \end{pmatrix} = \begin{pmatrix} -x_1 + 3x_1 \\ -x_1 + 3x_1 \\ -4x_1 + 13x_1 - 3x_1 \end{pmatrix} = \begin{pmatrix} 2x_1 \\ 2x_1 \\ 6x_1 \end{pmatrix} = 2 \begin{pmatrix} x_1 \\ x_1 \\ 3x_1 \end{pmatrix}$$

8.2.8

$$(a) A = \begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} 2-t & 4 \\ 5 & 3-t \end{pmatrix} = (2-t)(3-t) - 20$$

$$= 6 - 2t - 3t + t^2 - 20 = t^2 - 5t - 14.$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow t^2 - 5t - 14 = 0 \Rightarrow \frac{5 \pm \sqrt{25 + 56}}{2} = \frac{5 \pm \sqrt{81}}{2}$

$$\Rightarrow \frac{5 \pm 9}{2} \Rightarrow t_1 = 7, t_2 = -2.$$

$$V_7 : \begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 7 \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} 2x_1 + 4x_2 = 7x_1 \Rightarrow 4x_2 = 5x_1 \Rightarrow x_1 = \frac{4}{5}x_2 \\ 5x_1 + 3x_2 = 7x_2 \Rightarrow 5x_1 = 4x_2 \Rightarrow x_2 = \frac{5}{4}x_1 \end{cases}$$

$$V_7 = \left\{ \begin{pmatrix} x_1 \\ \frac{5}{4}x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} \right\rangle. \text{ we can check:}$$

$$\begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ \frac{5}{4}x_1 \end{pmatrix} = \begin{pmatrix} 2x_1 + 5x_1 \\ 5x_1 + \frac{15}{4}x_1 \end{pmatrix} = \begin{pmatrix} 7x_1 \\ \frac{35}{4}x_1 \end{pmatrix} = 7 \begin{pmatrix} x_1 \\ \frac{5}{4}x_1 \end{pmatrix}$$

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⑥

$$V_{-2}: \begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = -2 \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} 2x_1 + 4x_2 = -2x_1 \Rightarrow 4x_2 = -4x_1 \Rightarrow x_2 = -x_1 \\ 5x_1 + 3x_2 = -2x_2 \Rightarrow 5x_1 = -5x_2 \end{cases}$$

$$V_{-2} = \left\{ \begin{pmatrix} x_1 \\ -x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\rangle. \text{ we can check:}$$

$$\begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ -x_1 \end{pmatrix} = \begin{pmatrix} 2x_1 - 4x_1 \\ 5x_1 - 3x_1 \end{pmatrix} = \begin{pmatrix} -2x_1 \\ 2x_1 \end{pmatrix} = -2 \begin{pmatrix} x_1 \\ -x_1 \end{pmatrix}$$

$$(b) A = \begin{pmatrix} 1 & 2 \\ 2 & -2 \end{pmatrix}, P_A(t) = \det(A - tI) = \det \begin{pmatrix} 1-t & 2 \\ 2 & -2-t \end{pmatrix} = (1-t)(-2-t) - 4 \\ = -2 - t + 2t + t^2 - 4 = t^2 + t - 6 = (t-2)(t+3)$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow (t-2)(t+3) = 0 \Rightarrow \boxed{t=2}$  or  $\boxed{t=-3}$

$$V_2: \begin{pmatrix} 1 & 2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2x_1 \\ 2x_2 \end{pmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 = 2x_1 \Rightarrow 2x_2 = x_1 \Rightarrow x_2 = \frac{1}{2}x_1 \\ 2x_1 - 2x_2 = 2x_2 \Rightarrow 2x_1 = 4x_2 \Rightarrow x_1 = 2x_2 \end{cases}$$

$$V_2 = \left\{ \begin{pmatrix} x_1 \\ \frac{1}{2}x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right\rangle. \text{ we can check:}$$

$$\begin{pmatrix} 1 & 2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ \frac{1}{2}x_1 \end{pmatrix} = \begin{pmatrix} x_1 + x_1 \\ 2x_1 - x_1 \end{pmatrix} = \begin{pmatrix} 2x_1 \\ x_1 \end{pmatrix} = 2 \begin{pmatrix} x_1 \\ \frac{1}{2}x_1 \end{pmatrix}$$

$$V_{-3}: \begin{pmatrix} 1 & 2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -3x_1 \\ -3x_2 \end{pmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 = -3x_1 \Rightarrow 2x_2 = -4x_1 \Rightarrow x_2 = -2x_1 \\ 2x_1 - 2x_2 = -3x_2 \Rightarrow 2x_1 = -x_2 \Rightarrow x_2 = -2x_1 \end{cases}$$

$$V_{-3} = \left\{ \begin{pmatrix} x_1 \\ -2x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ -2 \end{pmatrix} \right\rangle. \text{ we can check:}$$

$$\begin{pmatrix} 1 & 2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ -2x_1 \end{pmatrix} = \begin{pmatrix} x_1 - 4x_1 \\ 2x_1 + 4x_1 \end{pmatrix} = \begin{pmatrix} -3x_1 \\ 6x_1 \end{pmatrix} = -3 \begin{pmatrix} x_1 \\ -2x_1 \end{pmatrix}$$

$$(c) \begin{pmatrix} 3 & 2 \\ -2 & 3 \end{pmatrix} = A \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} 3-t & 2 \\ -2 & 3-t \end{pmatrix}$$

$$= (3-t)^2 + 4 = 9 - 6t + t^2 + 4 = t^2 - 6t + 13$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow t^2 - 6t + 13 = 0$ . Using quadratic solver:

$$\frac{6 \pm \sqrt{36 - 52}}{2} = \frac{6 \pm \sqrt{-16}}{2} = \frac{6 \pm 4i}{2} \Rightarrow \begin{cases} 3 + 2i = t_1 \\ 3 - 2i = t_2 \end{cases}$$

$$V_{t_1}: \begin{pmatrix} 3 & 2 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = t_1 \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{cases} 3x_1 + 2x_2 = t_1 x_1 \Rightarrow 2x_2 = (t_1 - 3)x_1 \\ -2x_1 + 3x_2 = t_1 x_2 \Rightarrow -2x_1 = (t_1 - 3)x_2 \end{cases}$$

If  $x_1 = 1$  then  $x_2 = \frac{t_1 - 3}{2}$ , the same holds for  $t_2$ , hence

$$V_{t_1} = \left\{ \begin{pmatrix} x_1 \\ \frac{t_1 - 3}{2} \end{pmatrix} = \begin{pmatrix} x_1 \\ \frac{3 + 2i - 3}{2} \end{pmatrix} = \begin{pmatrix} x_1 \\ i \end{pmatrix} \right\} = \left\langle \begin{pmatrix} 1 \\ i \end{pmatrix} \right\rangle. \text{ We can check:}$$

$$\begin{pmatrix} 3 & 2 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ i \end{pmatrix} = \begin{pmatrix} 3x_1 + 2i \\ -2x_1 + 3i \end{pmatrix} = 3 + 2i \begin{pmatrix} x_1 \\ i \end{pmatrix}$$

$$V_{t_2} = \left\{ \begin{pmatrix} x_1 \\ \frac{t_1 - 3}{2} \end{pmatrix} = \begin{pmatrix} x_1 \\ \frac{3 - 2i - 3}{2} \end{pmatrix} = \begin{pmatrix} x_1 \\ -i \end{pmatrix} \right\} = \left\langle \begin{pmatrix} 1 \\ -i \end{pmatrix} \right\rangle.$$

(d)  $\begin{pmatrix} -1 & 2 & 2 \\ 2 & 2 & 2 \\ -3 & -6 & -6 \end{pmatrix} = A \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} -1-t & 2 & 2 \\ 2 & 2-t & 2 \\ -3 & -6 & -6-t \end{pmatrix}$

$$= (-1-t) \det \begin{pmatrix} 2-t & 2 \\ -6 & -6-t \end{pmatrix} - (2) \det \begin{pmatrix} 2 & 2 \\ -3 & -6-t \end{pmatrix} + (2) \det \begin{pmatrix} 2 & 2-t \\ -3 & -6 \end{pmatrix}$$

$$= (-1-t) [(2-t)(-6-t) + 12] - 2 [-12 - 2t + 6] + 2 [-12 - (-6 + 3t)]$$

$$= (-1-t) [-12 - 2t + 6t + t^2 + 12] - 2 [-2t - 6] + 2 [-12 + 6 - 3t]$$

$$= (-1-t) [t^2 + 4t] + 4t + 12 + 2 [-6 - 3t]$$

$$= -t^2 - 4t - t^3 - 4t^2 + 4t + 12 - 12 - 6t$$

$$= -t^3 - 5t^2 - 6t.$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow -t^3 - 5t^2 - 6t = 0 \Leftrightarrow t^3 + 5t^2 + 6t = 0$

$$\Leftrightarrow t(t^2 + 5t + 6) = 0 \Rightarrow t = 0 \text{ or } t^2 + 5t + 6 = 0 \Leftrightarrow (t+2)(t+3)$$

Therefore, there are three eigen values:  $t_1 = 0, t_2 = -2, t_3 = -3$

To find eigen vectors:

$$\begin{pmatrix} -1 & 2 & 2 \\ 2 & 2 & 2 \\ -3 & -6 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \lambda x_1 \\ \lambda x_2 \\ \lambda x_3 \end{pmatrix} \Rightarrow \begin{cases} -x_1 + 2x_2 + 2x_3 = \lambda x_1 \\ 2x_1 + 2x_2 + 2x_3 = \lambda x_2 \\ -3x_1 - 6x_2 - 6x_3 = \lambda x_3 \end{cases}$$

$$\Rightarrow \begin{cases} 2x_2 + 2x_3 = (\lambda + 1)x_1 \\ 2x_1 + 2x_3 = (\lambda - 2)x_2 \\ -3x_1 - 6x_2 = (\lambda + 6)x_3 \end{cases}$$

If  $\lambda = 0 \Rightarrow \begin{cases} 2x_2 + 2x_3 = x_1 \\ 2x_1 + 2x_3 = -2x_2 \Rightarrow 4x_2 + 4x_3 + 2x_3 = -2x_2 \Rightarrow 6x_3 = -6x_2 \Rightarrow x_3 = -x_2 \\ -3x_1 - 6x_2 = 6x_3 \Rightarrow -3x_1 - 6x_2 = -6x_2 \Rightarrow 3x_1 = 0 \Rightarrow x_1 = 0 \end{cases}$

$$V_0 = \left\{ \begin{pmatrix} 0 \\ x_2 \\ -x_2 \end{pmatrix} \mid x_2 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\rangle$$

$$\text{If } \lambda = -2 \Rightarrow \begin{cases} 2x_2 + 2x_3 = -x_1 \\ 2x_1 + 2x_3 = -4x_2 \Rightarrow -4x_2 - 4x_3 + 2x_3 = -4x_2 = (*) \\ -3x_1 - 6x_2 = 4x_3 \Rightarrow -3x_1 - 6x_2 = 0 \Rightarrow -3x_1 = 6x_2 \end{cases}$$

$$(*) \quad 0 = -2x_3 \Rightarrow x_3 = 0 \quad x_2 = -\frac{1}{2}x_1$$

$$V_{(-2)} = \left\{ \begin{pmatrix} x_1 \\ -\frac{1}{2}x_1 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ -\frac{1}{2} \\ 0 \end{pmatrix} \right\rangle$$

$$\text{If } \lambda = -3 \Rightarrow \begin{cases} 2x_2 + 2x_3 = -2x_1 \Rightarrow -x_2 - x_3 = x_1 \\ 2x_1 + 2x_3 = -5x_2 \Rightarrow -2x_2 - 2x_3 + 2x_3 = -5x_2 = (*) \\ -3x_1 - 6x_2 = 3x_3 \Rightarrow -3x_1 = 3x_3 \Rightarrow -x_1 = x_3 \Rightarrow x_1 = -x_3 \end{cases}$$

$$(*) \quad 0 = -3x_2 \Rightarrow x_2 = 0$$

$$V_{(-3)} = \left\{ \begin{pmatrix} x_1 \\ 0 \\ -x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \right\rangle$$

$$(e) \quad A = \begin{pmatrix} 3 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 1 & -1 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} 3-t & 2 & 1 \\ 0 & 1-t & 2 \\ 0 & 1 & -1-t \end{pmatrix}$$

$$= (3-t) \det \begin{pmatrix} 1-t & 2 \\ 1 & -1-t \end{pmatrix} - 2 \det \begin{pmatrix} 0 & 2 \\ 0 & -1-t \end{pmatrix} + 1 \det \begin{pmatrix} 0 & 1-t \\ 0 & 1 \end{pmatrix}$$

$$= (3-t)[(1-t)(-1-t) - 2] = (3-t)[-1-t+t^2-2]$$

$$= (3-t)(t^2-3) = 3t^2-9-t^3+3t = -t^3+3t^2+3t-9$$

Eigenvalues:  $P_A(t) = 0 \Rightarrow -t^3+3t^2+3t-9=0 \Rightarrow t^3-3t^2-3t+9=0$

$$= (t-3)(t^2-3) \Rightarrow t_1=3, t_2=\sqrt{3}, t_3=-\sqrt{3}$$

Eigenvectors:

$$\begin{pmatrix} 3 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = t \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \Rightarrow \begin{cases} 3x_1 + 2x_2 + 3x_3 = tx_1 \\ x_2 + 2x_3 = tx_2 \\ x_2 - x_3 = tx_3 \end{cases}$$

$$\Rightarrow \begin{cases} 2x_2 + 3x_3 = (t-3)x_1 \\ 2x_3 = (t-1)x_2 \\ x_2 = (t+1)x_3 \end{cases}$$

$$\text{If } t=3, \begin{cases} 2x_2 + 3x_3 = 0 \Rightarrow 2x_2 = -3x_3 \Rightarrow x_2 = -\frac{3}{2}x_3 \\ 2x_3 = 2x_2 \Rightarrow 2x_3 = -3x_3 \Rightarrow 5x_3 = 0 \Rightarrow x_3 = 0 \\ x_2 = 4x_3 \Rightarrow x_2 = 0 \end{cases}$$

$$V_3 = \left\{ \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\rangle$$

If  $t = \sqrt{3}$

$$\begin{cases} 2x_2 + 3x_3 = (\sqrt{3}-3)x_1 \\ 2x_3 = (\sqrt{3}-1)x_2 \Rightarrow 2x_3 = (\sqrt{3}-1)(\sqrt{3}+1)x_3 = 2x_3 \Rightarrow 2x_3 = 2x_3 \Rightarrow x_3 = x_3 \\ x_2 = (\sqrt{3}+1)x_3 \Rightarrow \frac{x_2}{\sqrt{3}+1} = x_3 \end{cases}$$

$$x_1 = \frac{2x_2 + 3x_3}{\sqrt{3}-3} = \frac{2(\sqrt{3}+1)x_3 + 3x_3}{\sqrt{3}-3} = \frac{2\sqrt{3}x_3 + 2x_3 + 3x_3}{\sqrt{3}-3} = \frac{x_3(2\sqrt{3}+5)}{\sqrt{3}-3}$$

$$v_{\sqrt{3}} = \left\langle \begin{pmatrix} \frac{x_3(2\sqrt{3}+5)}{\sqrt{3}-3} \\ \frac{\sqrt{3}+1}{\sqrt{3}+1} x_3 \\ x_3 \end{pmatrix} \right\rangle, \text{ likewise, replacing for } t = -\sqrt{3}$$

$$v_{-\sqrt{3}} = \left\langle \begin{pmatrix} \frac{x_3(-2\sqrt{3}+5)}{\sqrt{3}-3} \\ \frac{-\sqrt{3}+1}{\sqrt{3}+1} x_3 \\ x_3 \end{pmatrix} \right\rangle.$$

(P)  $A = \begin{pmatrix} -1 & 4 & -2 \\ -3 & 4 & 0 \\ -3 & 1 & 3 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} -1-t & 4 & -2 \\ -3 & 4-t & 0 \\ -3 & 1 & 3-t \end{pmatrix}$

$$= (-1-t) \det \begin{pmatrix} 4-t & 0 \\ 1 & 3-t \end{pmatrix} - 4 \det \begin{pmatrix} -3 & 0 \\ -3 & 3-t \end{pmatrix} - 2 \det \begin{pmatrix} -3 & 4-t \\ -3 & 1 \end{pmatrix}$$

$$= (-1-t)(4-t)(3-t) - 4(-3)(3-t) - 2(-3 - (-3)(4-t))$$

$$= (-1-t)(4-t)(3-t) + 36 - 12t - 2(-3 - (-12 + 3t))$$

$$= (-1-t)(4-t)(3-t) + 36 - 12t - 2(9 - 3t)$$

$$= (-1-t)(4-t)(3-t) + 36 - 12t - 18 + 6t$$

$$= (-1-t)(4-t)(3-t) + 18 - 6t$$

$$= (-1-t)(12 - 4t - 3t + t^2) + 18 - 6t$$

$$= -12 + 4t + 3t - t^2 - 12t + 4t^2 + 3t^2 - t^3 + 18 - 6t$$

$$= -t^3 + 6t^2 - 11t + 6$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow -t^3 + 6t^2 - 11t + 6 = 0 \Leftrightarrow t^3 - 6t^2 + 11t - 6 = 0$

$\Leftrightarrow (t-1)(t-2)(t-3) = 0$ , the eigen values are 1, 2, 3

Eigenvectors:

$$\begin{pmatrix} -1 & 4 & -2 \\ -3 & 4 & 0 \\ -3 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \lambda x_1 \\ \lambda x_2 \\ \lambda x_3 \end{pmatrix} \Rightarrow \begin{cases} -x_1 + 4x_2 - 2x_3 = \lambda x_1 \\ -3x_1 + 4x_2 = \lambda x_2 \\ -3x_1 + x_2 + 3x_3 = \lambda x_3 \end{cases}$$

$$\Rightarrow \begin{cases} 4x_2 - 2x_3 = (\lambda+1)x_1 \\ -3x_1 = (\lambda-4)x_2 \Rightarrow x_1 = \frac{(\lambda-4)}{-3} x_2 \\ -3x_1 + x_2 = (\lambda-3)x_3 \end{cases}$$

$$\text{If } \lambda = 1 \Rightarrow \begin{cases} 4x_2 - 2x_3 = 2x_1 \\ -3x_1 = -3x_2 \Rightarrow x_1 = x_2 \\ -3x_1 + x_2 = -2x_3 \end{cases} \quad \begin{matrix} \downarrow \\ -3x_1 + x_1 = -2x_3 \Rightarrow -2x_1 = -2x_3 \\ \Rightarrow x_1 = x_3 = x_2 \end{matrix}$$

$$V_1 = \left\{ \begin{pmatrix} x_1 \\ x_1 \\ x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle$$

$$\text{If } \lambda = 2 \Rightarrow \begin{cases} 4x_2 - 2x_3 = 3x_1 \\ -3x_1 = -2x_2 \Rightarrow x_2 = \frac{3}{2}x_1 \\ -3x_1 + x_2 = -x_3 \end{cases} \quad \begin{matrix} \downarrow \\ -3x_1 + \frac{3}{2}x_1 = -x_3 \Rightarrow x_1(-3 + \frac{3}{2}) = -x_3 \\ -\frac{3}{2}x_1 = -x_3 \Rightarrow x_3 = \frac{3}{2}x_1 \end{matrix}$$

$$V_2 = \left\{ \begin{pmatrix} x_1 \\ \frac{3}{2}x_1 \\ \frac{3}{2}x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ \frac{3}{2} \\ \frac{3}{2} \end{pmatrix} \right\rangle$$

$$\text{If } \lambda = 3 \Rightarrow \begin{cases} 4x_2 - 2x_3 = 4x_1 \\ -3x_1 = -x_2 \Rightarrow -3x_1 = -3x_1 \Rightarrow x_1 = x_1 \\ -3x_1 + x_2 = 0 \Rightarrow -3x_1 = -x_2 \Rightarrow x_2 = 3x_1 \end{cases}$$

$$4(3x_1) - 2x_3 = 4x_1 \Rightarrow 12x_1 - 4x_1 = 2x_3 \Rightarrow 8x_1 = 2x_3 \Rightarrow 4x_1 = x_3$$

$$V_3 = \left\{ \begin{pmatrix} x_1 \\ 3x_1 \\ 4x_1 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} 1 \\ 3 \\ 4 \end{pmatrix} \right\rangle$$

8.2.9.  $V = n$ -dimensional v.s.  $L: V \rightarrow V$  a linear map.  $P_A(t)$  has  $n$  distinct roots. Show that  $V$  has a basis consisting of eigenvectors of  $A$ .

Pf: By definition,  $P_A(t) = \det(A - tI)$ . If  $\det(A - tI) = 0$  has  $n$  distinct roots, then it looks like  $(t - a_1)(t - a_2) \cdots (t - a_n) = 0$ . For some  $a_i$ , possibly all equal. It suffices to show that the  $n$  eigenvectors associated with each eigenvalue (i.e., each  $a_i$ ) are independent. If so, then we will have  $n$  independent vectors on an  $n$ -dimensional v.s. which imply that these are a basis.

Each root of  $P_A(t)$  correspond to an eigenvalue. Each eigenvalue has a non-zero eigenvector. Let  $v_1, \dots, v_n$ , ( $v_i$ ) be the eigenvector with eigenvalue  $i$ . TAKE A LINEAR combination:

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0, \quad \text{Apply } T \text{ in both sides:}$$

$$T(c_1 v_1 + c_2 v_2 + \dots + c_n v_n) = T(0) \quad \text{By linearity and the fact } T(0) = 0$$

$$c_1 T(v_1) + c_2 T(v_2) + \dots + c_n T(v_n) = 0 \quad \text{Eigenvector: } T(v_i) = a_i v_i \quad \forall i$$

$$c_1 a_1 v_1 + c_2 a_2 v_2 + \dots + c_n a_n v_n = 0 \quad \text{But } v_i \neq 0 \quad \forall i, \text{ hence}$$

$$c_1 a_1 = c_2 a_2 = \dots = c_n a_n = 0 \Rightarrow \{v_1, \dots, v_n\} \text{ is independent and a basis.}$$

8.2.10. Let  $A$  be a square matrix. Show that the eigenvalues of  ${}^tA$  are the same as those of  $A$ .

Pf: By previous work (page 172) <sup>(Theorem 7.5)</sup>, we know that the determinant of a matrix  $A$  is equal to the determinant of its transpose. Hence,

$$P_A(t) = \det(A - I\lambda) = P_{{}^tA}(t) = \det({}^tA - I\lambda)$$

the eigenvalues are the roots of  $P_A(t)$ , which are the same roots of  $P_{{}^tA}(t)$ . Hence, the eigenvalues of  $A$  are the same as the eigenvalues of  ${}^tA$ .

8.2.11 Let  $A$  be an invertible matrix. If  $\lambda$  is an eigenvalue of  $A$ , show that  $\lambda \neq 0$  and that  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ .

Pf: By hypothesis,  $\lambda$  is an eigenvalue of  $A$ , i.e.,

$$Av = \lambda v, \text{ for some } v \neq 0.$$

$$A^{-1}(Av) = A^{-1}(\lambda v), \text{ applying } A^{-1} \text{ to both sides}$$

$$(A^{-1}A)v = \lambda(A^{-1}v), \text{ grouping and linearity of } A^{-1}$$

$$Iv = \lambda A^{-1}v, \text{ By definition of inverse.}$$

$$v = \lambda A^{-1}v, \text{ dividing by } \lambda, \text{ which we assume to be } \lambda \neq 0$$

$$\frac{1}{\lambda}v = A^{-1}v \Rightarrow \frac{1}{\lambda} \text{ is an eigenvalue of } A^{-1}.$$

8.2.12. Let  $V = \langle \{ \sin t, \cos t \} \rangle$  <sup>over  $\mathbb{R}$</sup> . Does  $D: V \rightarrow V$ ,  $D$  is the derivative, have any non-zero eigenvectors in  $V$ ? If so, which?

Solution: the matrix of the derivative with respect to  $\{ \sin t, \cos t \}$  is:

$$D(\sin t) = \cos t = 0 \cdot \sin t + 1 \cdot \cos t \Rightarrow D = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$D(\cos t) = -\sin t = -1 \cdot \sin t + 0 \cdot \cos t$$

$$\text{we can check that indeed } D(\sin t) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \cos t$$

$$D(\cos t) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} = -\sin t$$

Hence, an eigenvector of  $D$  correspond with an eigen vector of this matrix:

$$P_D(t) = \det(D - \lambda I) = \det \begin{pmatrix} -\lambda & -1 \\ 1 & -\lambda \end{pmatrix} = \lambda^2 + 1 \text{ the eigen values satisfy:}$$

$$P_D(t) = 0 \Leftrightarrow \lambda^2 + 1 = 0, \text{ which has no real roots.}$$



Therefore,  $D$  (the derivative) over  $\mathbb{R}$  has no non-zero eigenvectors.

8.2.13. Show that the functions  $\sin(kx)$  and  $\cos(kx)$  are eigenvectors for  $D^2$ . What are the eigenvalues?

Solution: Apply  $D^2$  to each function:

$$D^2(\sin kx) = kD(\cos kx) = -k^2 \sin kx$$

Hence,  $\sin kx$  is an eigenvector with eigenvalue  $-k^2$

$$D^2(\cos kx) = -kD(\sin kx) = -k^2 \cos kx$$

Hence,  $\cos kx$  is an eigenvector with eigenvalue  $-k^2$

8.2.15 Let  $A, B$  be square matrices of the same size.

Show that the eigenvalues of  $AB$  are the same as the eigenvalues of  $BA$ .

Solution: By definition, an eigenvalue  $\lambda$  of  $AB$  is:

$$\begin{aligned} (AB)v &= \lambda v && \text{operating by } B \text{ in both sides} \\ B(AB)v &= B(\lambda v) && \text{Associativity and linearity of } B \\ (BA)(Bv) &= \lambda(Bv) \end{aligned}$$

$\Rightarrow \lambda$  is an eigenvalue of  $BA$  with eigenvector  $Bv$ .

If we operate instead  $(BA)v = \lambda v \Rightarrow (AB)Av = \lambda(Av)$

$\Rightarrow \lambda$  is an eigenvalue of  $AB$  with eigenvector  $Av$ .

### Additional Exercises:

1) Show that  $T: V \rightarrow V$  is diagonalizable iff  $V$  is a direct sum of the eigenspaces of  $T$ .

Pf: By definition, a linear mapping  $T: V \rightarrow V$  is diagonalizable iff  $\exists$  basis  $\{v_1, \dots, v_n\}$  of  $V$  and  $\lambda_1, \dots, \lambda_n \in \mathbb{K}$  so that  $T(v_i) = \lambda_i v_i \quad \forall i=1, \dots, n$

$(\Rightarrow)$  Assume  $T$  is diagonalizable, show  $V = V_{\lambda_1} \oplus V_{\lambda_2} \oplus \dots \oplus V_{\lambda_n}$

To show direct sum we need to show two properties:

(1) Show every  $v \in V$  can be written as  $v = \sum w_i$  where  $w_i \in V_{\lambda_i}$ .

Because  $\{v_1, \dots, v_n\}$  is a basis, every  $v \in V$  can be written as:

$$v = \lambda_1 v_1 + \lambda_2 v_2 + \dots + \lambda_n v_n \quad \text{But, } T(v_i) = \lambda_i v_i. \text{ Hence } \lambda_i v_i \in V_{\lambda_i}$$

$$(2) V_{\lambda_1} \cap V_{\lambda_2} \cap \dots \cap V_{\lambda_n} = \{\theta\}$$

Let  $z \in V_{\lambda_i} \quad \forall i=1, \dots, n$ . then,  $T(z) = \lambda_i z \quad \forall i=1, \dots, n$

$\Rightarrow$  Because not all  $\lambda_i$ s are zero  $\Rightarrow z = \theta$ .

Hence  $V = \bigoplus_{i=1}^n V_{\lambda_i}$ .

( $\Leftarrow$ ) Assume that  $V = \bigoplus_{i=1}^n V_{\lambda_i}$ . then  $\{v_1, \dots, v_n\}$  where  $v_i \in V_{\lambda_i}$  form a basis for  $V$ . But, by definition  $v_i \in V_{\lambda_i}$  iff  $T(v_i) = \lambda_i v_i$ . Hence,  $T$  is diagonalizable on account of the existence of the basis  $\{v_1, \dots, v_n\}$ .

(2) Let  $V$  be the v.s. of  $2 \times 2$  matrices with real entries.

Define  $T: V \rightarrow V$  by  $T(A) = B^{-1}AB$ , where  $B$  is the  $2 \times 2$  matrix whose first row is  $[0, 1]$  and whose second row is  $[1, 0]$ .

Find the eigenvalues and eigenvectors of  $T$ .

Solution:  $B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ ,  $B^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  because  $BB^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$

Hence,  $T: V \rightarrow V$ ,  $T(A) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ .

First, we need to compute the matrix associated with  $T$ .

Let  $\{A_{11}, A_{12}, A_{21}, A_{22}\}$  be the basis of v.s. of  $2 \times 2$  matrices, where  $A_{ij} = 1$  in  $(i, j)$  position and 0 everywhere else. then,

$$T(A_{11}) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = A_{22}$$

$$T(A_{12}) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = A_{21}$$

$$T(A_{21}) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = A_{12}$$

$$T(A_{22}) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = A_{11}$$

$$T(A_{11}) = 0A_{11} + 0A_{12} + 0A_{21} + 1A_{22}$$

$$T(A_{12}) = 0A_{11} + 0A_{12} + 1A_{21} + 0A_{22}$$

$$T(A_{21}) = 0A_{11} + 1A_{12} + 0A_{21} + 0A_{22}$$

$$T(A_{22}) = 1A_{11} + 0A_{12} + 0A_{21} + 0A_{22}$$

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The matrix of the linear transformation  $T$  is:

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} = A_T$$

We want to find eigenvalues and eigenvectors of  $A_T$ , i.e.,

$$A_T(v) = \lambda v \Rightarrow P_{A_T}(t) = \det(A_T - \lambda I) = \det \begin{pmatrix} -t & 0 & 0 & 1 \\ 0 & -t & 1 & 0 \\ 0 & 1 & -t & 0 \\ 1 & 0 & 0 & -t \end{pmatrix}$$

$$= (-t) \det \begin{pmatrix} -t & 1 & 0 \\ 1 & -t & 0 \\ 0 & 0 & -t \end{pmatrix} - 1 \det \begin{pmatrix} 0 & -t & 1 \\ 0 & 1 & -t \\ 1 & 0 & 0 \end{pmatrix}$$

$$= (-t) \left( (-t) \det \begin{pmatrix} -t & 0 \\ 0 & -t \end{pmatrix} - 1 \det \begin{pmatrix} 1 & 0 \\ 0 & -t \end{pmatrix} \right) - 1 \left( (t) \det \begin{pmatrix} 0 & -t \\ 1 & 0 \end{pmatrix} + 1 \det \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right)$$

$$= (-t) \left( (-t)(t^2) + t \right) - (t^2 - 1) = t^4 - t^2 - t^2 + 1 = t^4 - 2t^2 + 1$$

The eigenvalues satisfy:  $P_{A_T}(t) = 0 \Leftrightarrow t^4 - 2t^2 + 1 = 0$

$\Leftrightarrow (t-1)^2 (t+1)^2 = 0$ . The eigenvalues are  $+1$  and  $-1$ .

Eigenvectors:

For  $\lambda_{+1}$ :

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} \Rightarrow \begin{cases} w = x \\ z = y \\ y = z \\ x = w \end{cases}$$

$$V_{\lambda_{+1}} = \left\{ \begin{pmatrix} x \\ y \\ y \\ x \end{pmatrix} \mid x, y \in \mathbb{R} \right\} = \left\langle \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} \right\} \right\rangle$$

We can check:

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ y \\ x \end{bmatrix} = \begin{bmatrix} x \\ y \\ y \\ x \end{bmatrix} = 1 \cdot \begin{bmatrix} x \\ y \\ y \\ x \end{bmatrix}. \text{ In terms of the } 2 \times 2 \text{ matrices, } V_{\lambda_{+1}} = \left\{ \begin{pmatrix} x & y \\ y & x \end{pmatrix} \mid x, y \in \mathbb{R} \right\}.$$

We can also check this:

$$T \begin{pmatrix} x & y \\ y & x \end{pmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} x & y \\ y & x \end{pmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} y & x \\ x & y \end{pmatrix} = 1 \begin{pmatrix} x & y \\ y & x \end{pmatrix}$$

For  $\lambda = -1$ :

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} -x \\ -y \\ -z \\ w \end{bmatrix} \Rightarrow \begin{cases} w = -x \\ z = -y \\ y = -z \\ x = -w \end{cases}$$

$$V_{\lambda(-1)} = \left\{ \begin{pmatrix} x \\ -y \\ -x \\ -x \end{pmatrix} \mid x, y \in \mathbb{R} \right\} = \left\langle \left( \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right) \right\rangle$$

we can check:

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} -x \\ -y \\ -z \\ w \end{bmatrix} = -1 \begin{bmatrix} x \\ y \\ z \\ -w \end{bmatrix} \quad \text{In terms of } 2 \times 2 \text{ matrices:}$$
$$V_{\lambda(-1)} = \left\{ \begin{pmatrix} x & y \\ -y & -x \end{pmatrix} \mid x, y \in \mathbb{R} \right\}$$

we can also check this:

$$T \begin{pmatrix} x & y \\ -y & -x \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x & y \\ -y & -x \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} y & x \\ -x & -y \end{pmatrix} = \begin{pmatrix} -x & -y \\ y & x \end{pmatrix} = -1 \begin{pmatrix} x & y \\ -y & -x \end{pmatrix}$$

(3)  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$   $T = \begin{bmatrix} 0 & 2 \\ -1 & 0 \end{bmatrix}$ . Is  $T$  diagonalizable?

solution:

$$P_T(\lambda) = \det(T - \lambda I) = \det \begin{pmatrix} -\lambda & 2 \\ -1 & -\lambda \end{pmatrix} = \lambda^2 + 2.$$

Eigenvalues:  $P_T(\lambda) = 0 \Rightarrow \lambda^2 + 2 = 0 \Rightarrow \lambda = \pm\sqrt{-2}$ .

Hence, if  $T$  is viewed as  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , then  $T$  is not diagonalizable because it fails to have any eigen value.

On the contrary, if  $T$  is viewed as  $T: \mathbb{C}^2 \rightarrow \mathbb{C}^2$ , then:

$$P_T(\lambda) = 0 \Rightarrow \lambda = \pm\sqrt{2}i.$$

thus, we have two eigen values  $\lambda_1 = \sqrt{2}i$  and  $\lambda_2 = -\sqrt{2}i$

Eigenvectors:

$$\begin{bmatrix} 0 & 2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \sqrt{2}i \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow \begin{cases} 2x_2 = \sqrt{2}i x_1 \\ -x_1 = \sqrt{2}i x_2 \Rightarrow x_1 = -\sqrt{2}i x_2 \end{cases}$$

$$V_{\lambda_1} = \left\{ \begin{pmatrix} -\sqrt{2}i x_2 \\ -x_2 \end{pmatrix} \right\} = \left\langle \begin{pmatrix} -\sqrt{2}i \\ 1 \end{pmatrix} \right\rangle. \text{ we can check:}$$

$$\begin{bmatrix} 0 & 2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} -\sqrt{2}i x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_2 \\ \sqrt{2}i x_2 \end{bmatrix} = \sqrt{2}i \begin{bmatrix} -\sqrt{2}i x_2 \\ x_2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & z \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -\sqrt{z}i \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow \begin{cases} 2x_2 = -\sqrt{z}i x_1 \\ -x_1 = -\sqrt{z}i x_2 \Rightarrow x_1 = \sqrt{z}i x_2 \end{cases}$$

$$\sqrt{\lambda_2} = \left\{ \begin{pmatrix} \sqrt{z}i x_2 \\ x_2 \end{pmatrix} \right\} = \left\langle \begin{pmatrix} \sqrt{z}i \\ 1 \end{pmatrix} \right\rangle. \text{ We can check:}$$

$$\begin{bmatrix} 0 & z \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \sqrt{z}i x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_2 \\ -\sqrt{z}i x_2 \end{bmatrix} = -\sqrt{z}i \begin{bmatrix} \sqrt{z}i x_2 \\ x_2 \end{bmatrix}$$

Hence,  $\exists$  a basis  $\left\{ \begin{pmatrix} -\sqrt{z}i \\ 1 \end{pmatrix}, \begin{pmatrix} \sqrt{z}i \\ 1 \end{pmatrix} \right\}$  and  $\lambda_1 = \sqrt{z}i, \lambda_2 = -\sqrt{z}i$ , so that  $T(v_i) = \lambda_i v_i$ , for  $i=1,2$ .  $\Rightarrow T$  is diagonalizable in  $\mathbb{C}$ .

Section 8.4.

(15). Let  $V$  be a v.s. of dimension  $n$  over  $\mathbb{R}$ , with a positive definite scalar product.

Let  $A: V \rightarrow V$  be a symmetric linear map. Prove that the following conditions on  $A$  imply each other.

(a)  $\Rightarrow$  (b). Assume that all eigenvalues of  $A$  are  $> 0$ .

By the spectral theorem,  $V$  has an orthonormal basis consisting of eigenvectors. Let such a basis be  $\{v_1, \dots, v_n\}$ . Then, for any  $v \in V$ , we have

$$v = a_1 v_1 + a_2 v_2 + \dots + a_n v_n.$$

TAKE  $\langle Av, v \rangle = \langle A(a_1 v_1 + a_2 v_2 + \dots + a_n v_n), a_1 v_1 + a_2 v_2 + \dots + a_n v_n \rangle =$

By properties of linear map  $A$ :

$$= \langle a_1 A v_1 + a_2 A v_2 + \dots + a_n A v_n, a_1 v_1 + a_2 v_2 + \dots + a_n v_n \rangle =$$

But  $v_i$  is an eigenvector, hence

$$= \langle a_1 \lambda_1 v_1 + a_2 \lambda_2 v_2 + \dots + a_n \lambda_n v_n, a_1 v_1 + a_2 v_2 + \dots + a_n v_n \rangle =$$

By Bilinearity

$$= a_1^2 \lambda_1 \langle v_1, v_1 \rangle + a_1 a_2 \lambda_1 \langle v_1, v_2 \rangle + \dots + a_1 a_n \lambda_1 \langle v_1, v_n \rangle + a_2 a_1 \lambda_2 \langle v_2, v_1 \rangle + a_2^2 \lambda_2 \langle v_2, v_2 \rangle + \dots + a_2 a_n \lambda_2 \langle v_2, v_n \rangle + \dots + a_n a_1 \lambda_n \langle v_n, v_1 \rangle + a_n a_2 \lambda_n \langle v_n, v_2 \rangle + \dots + a_n^2 \lambda_n \langle v_n, v_n \rangle =$$

But,  $\{v_1, \dots, v_n\}$  is orthogonal  $\Rightarrow \langle v_i, v_j \rangle = 0 \ \forall i \neq j$

$$= a_1^2 \lambda_1 \langle v_1, v_1 \rangle + a_2^2 \lambda_2 \langle v_2, v_2 \rangle + \dots + a_n^2 \lambda_n \langle v_n, v_n \rangle$$

$\langle \cdot, \cdot \rangle$  is pos def. and  $v_i \neq 0 \ \forall i \Rightarrow \langle v_i, v_i \rangle > 0$  and  $a_i^2 > 0$  and, by hypothesis  $\lambda_i > 0 \ \forall i$ , hence

$$\langle Av, v \rangle = \sum_{i=1}^n a_i^2 \lambda_i \langle v_i, v_i \rangle > 0 \Rightarrow \langle Av, v \rangle > 0$$

(b)  $\Rightarrow$  (a). Assume that if  $v \in V, v \neq 0$ , then  $\langle Av, v \rangle > 0$

Let  $v$  ( $v \neq 0$ ) be an eigenvector with eigenvalue  $\lambda$  of  $A$  then

$$Av = \lambda v \Rightarrow Av - \lambda v = 0$$

$\langle, \rangle$  is a pos. def. scalar product, hence,

$$\langle 0, 0 \rangle = 0 \Rightarrow \langle Av - \lambda v, Av - \lambda v \rangle = 0$$

$$\text{By bilinearity} \Rightarrow \langle Av, Av \rangle - \langle Av, \lambda v \rangle - \langle \lambda v, Av \rangle + \langle \lambda v, \lambda v \rangle =$$

$$\text{Symmetry of } \langle, \rangle \Rightarrow \langle Av, Av \rangle - \lambda \langle Av, v \rangle - \lambda \langle Av, v \rangle + \lambda^2 \langle v, v \rangle$$

$$\text{But, } Av = \lambda v \quad \langle Av, Av \rangle - 2\lambda \langle Av, v \rangle + \lambda^2 \langle v, v \rangle =$$

$$\Rightarrow \lambda \langle Av, v \rangle - 2\lambda \langle Av, v \rangle + \lambda^2 \langle v, v \rangle =$$

$$\Rightarrow \lambda^2 \langle v, v \rangle - \lambda \langle Av, v \rangle = 0$$

$$\Rightarrow \lambda^2 \langle v, v \rangle = \lambda \langle Av, v \rangle$$

$$\text{Assuming } \lambda \neq 0 \Rightarrow \lambda \langle v, v \rangle = \langle Av, v \rangle$$

By hypothesis  $\langle Av, v \rangle > 0$  and  $\langle v, v \rangle > 0$  because  $v \neq 0$

$\Rightarrow \lambda > 0$  for all eigenvalues of  $A$ .

(8.4.24) Let  $V$  be a v.s. of dimension  $n$  over  $\mathbb{R}$ , with a positive definite scalar product. Let  $A: V \rightarrow V$  be a symmetric operator.

To show  $A$  has only one eigenvalue, suppose  $A$  has two distinct eigenvalues  $\lambda_1$  and  $\lambda_2$ . Assuming that  $A$  has no invariant subspaces other than  $\emptyset$  and  $V$ , we get a contradiction because  $V_{\lambda_1}$  is such that if  $v \in V_{\lambda_1}$  then  $Av \in V_{\lambda_1}$ , hence  $V_{\lambda_1}$  is stable under  $A$  and so is  $V_{\lambda_2}$ . Hence,  $A$  has only one eigenvalue. Then, using the spectral theorem, we have an orthonormal basis  $\{v_1, \dots, v_n\}$  for  $V$ .

$$\text{Take } Av = A \sum_{i=1}^n a_i v_i = \sum_{i=1}^n a_i Av_i = \sum_{i=1}^n a_i \lambda v_i = \lambda \sum_{i=1}^n a_i v_i = \lambda v$$

$$\Rightarrow A = \lambda I \text{ because } \lambda I v = \lambda v.$$

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Additional Exercises:

$$1) A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \Rightarrow P_A(t) = \det(A - tI) = \det \begin{pmatrix} 2-t & -1 \\ -1 & 2-t \end{pmatrix}$$

$$= (2-t)^2 - 1 = 4 - 4t + t^2 - 1 = t^2 - 4t + 3 = (t-3)(t-1)$$

$\Rightarrow$  the eigenvalues of  $A$  are  $\lambda_1 = 3, \lambda_2 = 1$ .

The critical values of  $f(x) = \frac{\langle Ax, x \rangle}{\langle x, x \rangle}$  are, by theorem in class, precisely the eigenvalues 3, 1.

We can check this using calculus:

$$f(x) = \frac{\langle Ax, x \rangle}{\langle x, x \rangle} = \frac{\langle \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \rangle}{\langle \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \rangle} = \frac{\langle \begin{pmatrix} 2x_1 - x_2 \\ -x_1 + 2x_2 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \rangle}{x_1^2 + x_2^2}$$

$\Rightarrow f(x) = \frac{2x_1^2 - 2x_1x_2 + 2x_2^2}{x_1^2 + x_2^2}$ . To find critical points, set

$\nabla f = 0 \Rightarrow \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2} \right) = (0, 0)$ .

$$\frac{\partial f}{\partial x_1} = \frac{(4x_1 - 2x_2)(x_1^2 + x_2^2) - (2x_1^2 - 2x_1x_2 + 2x_2^2)(2x_1)}{(x_1^2 + x_2^2)^2} = 0$$

$$\begin{aligned} \Rightarrow (4x_1 - 2x_2)(x_1^2 + x_2^2) - (2x_1^2 - 2x_1x_2 + 2x_2^2)(2x_1) &= 0 \\ = (4x_1^3 + 4x_1x_2^2 - 2x_1^2x_2 - 2x_2^3) - (4x_1^3 - 4x_1^2x_2 + 4x_1x_2^2) & \\ = \cancel{4x_1^3} + \cancel{4x_1x_2^2} - 2x_1^2x_2 - 2x_2^3 - \cancel{4x_1^3} + 4x_1^2x_2 - \cancel{4x_1x_2^2} & \\ = 2x_1^2x_2 - 2x_2^3 \Rightarrow \boxed{\frac{\partial f}{\partial x_1} = 0 = x_1^2x_2 - x_2^3} & \end{aligned}$$

$\Rightarrow x_2^3 = x_1^2x_2$ , the candidate points are  $(0,0), (1,1), (-1,1), (1,-1)$  and  $(-1,-1)$

Likewise,

$$\frac{\partial f}{\partial x_2} = \frac{(-2x_1 + 4x_2)(x_1^2 + x_2^2) - (2x_1^2 - 2x_1x_2 + 2x_2^2)(2x_2)}{(x_1^2 + x_2^2)^2} = 0$$

$\Rightarrow$

$$\begin{aligned}
&= (-2x_1^3 - 2x_1x_2^2 + 4x_1^2x_2 + 4x_2^3) - (4x_1^2x_2 - 4x_1x_2^2 + 4x_2^3) \\
&= -2x_1^3 - 2x_1x_2^2 + \cancel{4x_1^2x_2} + \cancel{4x_2^3} - \cancel{4x_1^2x_2} + \cancel{4x_1x_2^2} - \cancel{4x_2^3} \\
&= -2x_1^3 + 2x_1x_2^2
\end{aligned}$$

$$\Rightarrow \boxed{\frac{\partial f}{\partial x_2} = 0 = x_1x_2^2 - x_1^3} \Rightarrow x_1^3 = x_1x_2^2$$

the candidate points are  $(0,0), (1,1), (-1,1), (1,-1)$  and  $(-1,-1)$

Exactly the same as for  $\frac{\partial f}{\partial x_1}$ .

to find critical values, we plug the candidate points back into  $f(x)$ :

$f(0,0)$  is not defined.

$$f(1,1) = \frac{2-2+2}{2} = 1 = f(-1,-1) \Rightarrow \text{correspond to eigenvalue 1}$$

$$f(-1,1) = \frac{2+2+2}{2} = 3 = f(1,-1) \Rightarrow \text{correspond to eigenvalue 3}$$

(2)  $A = \begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$ , the critical values are given by:

$$\begin{aligned}
P_A(t) = 0 &\Rightarrow \det(A - tI) = \det \begin{pmatrix} 1-t & -1 & 0 \\ -1 & 2-t & -1 \\ 0 & -1 & 1-t \end{pmatrix} \\
&= (1-t) \det \begin{pmatrix} 2-t & -1 \\ -1 & 1-t \end{pmatrix} + \det \begin{pmatrix} -1 & -1 \\ 0 & 1-t \end{pmatrix}
\end{aligned}$$

$$= (1-t)[(2-t)(1-t) - 1] + t - 1 = (1-t)[2 - 2t - t + t^2 - 1] + t - 1$$

$$= (1-t)(t^2 - 3t + 1) + t - 1 = t^2 - 3t + 1 - t^3 + 3t^2 - t + t - 1$$

$$= -t^3 + 4t^2 - 3t$$

Eigenvalues:  $P_A(t) = 0 \Leftrightarrow -t^3 + 4t^2 - 3t = 0 \Leftrightarrow t^3 - 4t^2 + 3t = 0$

$$t(t^2 - 4t + 3) = 0 \Leftrightarrow t(t-1)(t-3) = 0$$

Hence, the eigenvalues are  $t=0, t=1$  and  $t=3$ .

By previous theorem, these are the critical values for

$$f(x) = \frac{\langle Ax, x \rangle}{\langle x, x \rangle}, \text{ where } x \in \mathbb{R}^3.$$



Section 8.3.

(3) Find the maximum and minimum of the function

$$f(x, y) = 3x^2 + 5xy - 4y^2$$

on the unit circle.

Solution: First, find the matrix associated to  $f$ ; i.e.,

$$(x \ y) \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 3x^2 + 5xy - 4y^2$$

$$\Rightarrow (x \ y) \begin{pmatrix} ax+by \\ bx+dy \end{pmatrix} = 3x^2 + 5xy - 4y^2$$

$$\Rightarrow ax^2 + 2bxy + dy^2 = 3x^2 + 5xy - 4y^2$$

$$\Rightarrow a=3, \quad b=\frac{5}{2}, \quad d=-4.$$

we obtain the matrix

$$A = \begin{pmatrix} 3 & 5/2 \\ 5/2 & -4 \end{pmatrix}$$

To find its critical values, we compute its eigenvalues:

$$P_A(t) = \det(A - tI) = \det \begin{pmatrix} 3-t & 5/2 \\ 5/2 & -4-t \end{pmatrix} = (3-t)(-4-t) - \frac{25}{4}$$

$$= -12 - 3t + 4t + t^2 - \frac{25}{4} = t^2 + t - \frac{73}{4}$$

Eigenvalues  $\Rightarrow t^2 + t - \frac{73}{4} = 0$  Using quadratic solver:

$$\frac{-1 \pm \sqrt{1+73}}{2} = \frac{-1 \pm \sqrt{74}}{2}, \quad \text{Hence, the eigenvalues are}$$

$$\frac{-1 - \sqrt{74}}{2}, \quad \frac{-1 + \sqrt{74}}{2}.$$

the maximum is  $\frac{-1 + \sqrt{74}}{2}$ , the minimum is  $\frac{-1 - \sqrt{74}}{2}$ .

### Additional Exercise Corrected:

(a) the bijection  $\psi: A \rightarrow A'$ , where  $A$  and  $A'$  satisfy (1) and (2) can be defined as:

$$\psi(i, j) = \begin{cases} (i, j) & \text{if } (i, j) \in A' \\ (j, i) & \text{if } (i, j) \notin A' \end{cases}$$

this is a bijection. Proof:

(1)  $\psi$  is injective: Let  $\psi(i, j) = \psi(k, l)$ . By definition of  $\psi$ , if  $(i, j) \in A'$ , then  $\psi(i, j) = (i, j) = \psi(k, l) \Rightarrow (i, j) = (k, l)$ .  
If  $(i, j) \notin A'$ , then  $\psi(i, j) = (j, i) = \psi(k, l) \Rightarrow (i, j) = (k, l)$ .

A symmetric case occurs for  $(k, l) \in A'$  and  $(k, l) \notin A'$ .

(2)  $\psi$  is surjective:  $\forall (k, l) \in A', \exists (i, j) \in A$  s.t.  $\psi(i, j) = (k, l)$ .  
Let  $(k, l) \in A'$ . then, by definition of  $\psi$ , and conditions on  $A, A'$ , either  $(k, l) \in A$ , in which case  $\psi(k, l) = (k, l)$ , OR  $(l, k) \in A$ , in which case  $\psi(l, k) = (k, l)$ .

(1) & (2)  $\Rightarrow$  Bijectivity.

(b)  $f$  is a permutation of  $\{1, 2, \dots, n\}$ .

$\prod_{(i, j) \in A} \frac{x_{f(i)} - x_{f(j)}}{x_i - x_j}$  = using the bijection  $\psi$ , we have two possibilities, either we are dealing with the identity, in which case is true that:

$$\prod_{(i, j) \in A} \frac{x_{f(i)} - x_{f(j)}}{x_i - x_j} = \prod_{(i, j) \in A'} \frac{x_{f(i)} - x_{f(j)}}{x_i - x_j}$$

Or, we are dealing with the case in which  $\psi(i, j) = (j, i)$ , in which case:

$$\begin{aligned} \prod_{(i, j) \in A} \frac{x_{f(i)} - x_{f(j)}}{x_i - x_j} &= \prod_{\psi(i, j) \in A} \frac{x_{f(j)} - x_{f(i)}}{x_j - x_i} = \prod_{(j, i) \in A} \frac{(-1) x_{f(j)} - (-1) x_{f(i)}}{(-1) x_j - (-1) x_i} \\ &= \prod_{(j, i) \in A} \frac{x_{f(i)} - x_{f(j)}}{x_i - x_j} \end{aligned}$$

(c) if  $g$  is another permutation.

$$\prod_{i < j} \frac{X_{f(g(i))} - X_{f(g(j))}}{X_{g(i)} - X_{g(j)}} = \prod_{i < j} \frac{X_{f(g(\tilde{\Psi}(i)))} - X_{f(g(\tilde{\Psi}(j)))}}{X_{g(\tilde{\Psi}(i))} - X_{g(\tilde{\Psi}(j))}} = (*)$$

where  $\tilde{\Psi}(i) =$  the component  $i$  of  $\Psi(i, j)$ ,

Hence, If we are on case 1 of  $\Psi(i, j)$ , then

$$(*) = \prod_{i < j} \frac{X_{f(i)} - X_{f(j)}}{X_i - X_j}$$

Otherwise, If we are on case 2 of  $\Psi$ , then

$$\begin{aligned} (*) &= \prod_{i < j} \frac{X_{f(j)} - X_{f(i)}}{X_j - X_i} = \text{multiply and divide by } -1 \\ &= \prod_{i < j} \frac{(-1)(X_{f(j)} - X_{f(i)})}{(-1)(X_j - X_i)} = \prod_{i < j} \frac{X_{f(i)} - X_{f(j)}}{X_i - X_j} \end{aligned}$$

which shows what we wanted to show.