

6 elements of statistical inference (1) Parameter Space Θ (2) Sample space X (3) Family of prob. distributions on X (4) Action Space (5) Loss function $L: \Theta \times A \rightarrow \mathbb{R}$, (6) a set \mathcal{D} of decision rules. $\mathcal{D} = \{d: X \rightarrow A\}$

Risk Function: if state of nature $\theta \in \Theta$ obtains, then the RISK associated with non-randomized decision rule d is $R(\theta, d) = E_{\theta} L(\theta, d(X)) = \int_{X \in \mathcal{X}} L(\theta, d(x)) f(x; \theta) dx$. Associated with each d is a risk function: $R(\cdot, d): \Theta \rightarrow \mathbb{R}$.

the randomized decision rule $d^* = \lambda d_i + (1-\lambda) d_j$ is the rule that takes action $d_i(x)$ with prob. λ and action $d_j(x)$ with prob. $(1-\lambda)$. the risk function of d^* is: $R(\theta, d^*) = \lambda R(\theta, d_i) + (1-\lambda) R(\theta, d_j)$.

KEY NOTION: different decision rules should be compared by comparing their risk function (as function of θ)

common loss function: abs. error $L(\theta, a) = |\theta - a|$, squared error loss $L(\theta, a) = (\theta - a)^2$

Admissibility: Let d_1, d_2 be decision rules s.t.: $R(\theta, d_1) \leq R(\theta, d_2), \forall \theta \in \Theta$, with $R(\theta, d_1) < R(\theta, d_2)$ for at least one $\theta \in \Theta$, then, d_1 strictly dominates d_2 [$d_1 \succ d_2$]. If d is strictly dominated by some other rule, then d is inadmissible, otherwise it is admissible.

UMR: let \mathcal{D}_0 be a collection of decision rules. the rule $d^* \in \mathcal{D}_0$ has uniformly min. risk in \mathcal{D}_0 iff $R(\theta, d^*) \leq R(\theta, d), \forall \theta \in \Theta$ and $\forall d \in \mathcal{D}_0$. [UMR may be impossible to obtain. two strategies then:]

I. impartiality principles: restrict attention to "reasonable rules" that have constant risk so minimizing them is equivalent to minimizing the single risk value. A unbiased rules, d is L -unbiased iff: $E_{\theta} L(\theta', d(X)) \geq E_{\theta} L(\theta, d(X)) = R(\theta, d), \forall \theta, \theta' \in \Theta$, where $\theta =$ true state of nature, $\theta' =$ some other state.

B. Equivariant rules. II Relax the optimality criterion: A minimax principle: a decision rule d is minimax iff $\sup_{\theta} R(\theta, d) \leq \sup_{\theta} R(\theta, d), \forall d \in \mathcal{D}$. Minimax principle: use minimax rule. This is a very conservative principle.

B. BAYES principle: let π be a prob. dist. on Θ . Bayes risk of d : $r(d; \pi) = \int_{\Theta} R(\theta, d) \pi(\theta) d\theta$. Bayes principle = choose d_{π} , the rule that minimizes the Bayes risk for a given $\pi(\theta)$: $\int_{\Theta} R(\theta, d_{\pi}) \pi(\theta) d\theta \leq \int_{\Theta} R(\theta, d) \pi(\theta) d\theta, \forall d \in \mathcal{D}$

THEOREM: d_{π} Bayes rule with constant risk $\Rightarrow d_{\pi}$ is MINIMAX.

Admissibility of Bayes Rules **THM 2.3**: Assume $\Theta = \{\theta_1, \dots, \theta_n\}$ and $\pi(\cdot)$ is a prob. dist. on Θ . then, a Bayes rule w.r.t. π is admissible. **THM 2.4**: If a Bayes rule is unique then it is admissible.

THM 2.5: d_{π} is admissible (continuous case).

BAYESIAN INFERENCE: Treat θ as a r.v. (1) prior distribution of θ (2) inference based on posterior dist. as a function of d .

POSTERIOR $\pi(\theta|x) = \theta|x \propto$ prior \times likelihood $= \pi(\theta) f(x; \theta) \Rightarrow \theta|x = \frac{\pi(\theta) f(x; \theta)}{\int_{\Theta} \pi(\theta) f(x; \theta) d\theta}$

To find Bayes rule, d_{π} , define $d_{\pi}(x)$ for each $x \in X$ to minimize expected posterior loss $\int_{\Theta} L(\theta, d(x)) \pi(\theta|x) d\theta$. The expected posterior loss is:

CASE 1: Bayesian approach to hypothesis testing: $L(\theta, a_i)$: $\int_{\Theta} L(\theta, d(x)) \pi(\theta|x) d\theta = \begin{cases} \int_{\Theta_1} \pi(\theta) d\theta \rightarrow \text{posterior prob. of } \Theta_1 & \text{if } d(x) = a_0 \\ \int_{\Theta_0} \pi(\theta) d\theta \rightarrow \text{posterior prob. of } \Theta_0 & \text{if } d(x) = a_1 \end{cases}$ Bayes rule: choose Θ_i with the larger posterior prob.

CASE 2: Point estimation (a) For squared error loss $L(\theta, a) = (\theta - a)^2$, the expected posterior loss is minimized [Bayes rule] by choosing $d(x) = \int_{\Theta} \theta \pi(\theta|x) d\theta$, the posterior mean $E[\text{mean of } \pi(\theta|x)]$. (b) For absolute error loss $L(\theta, a) = |\theta - a|$, the Bayes rule is the posterior median of θ . $\int_{\Theta_0} \pi(\theta) d\theta = \int_{\Theta_1} \pi(\theta) d\theta = \frac{1}{2}$

HYPOTHESIS TESTING: partition Θ into Θ_0, Θ_1 . Test hypothesis: $H_0: \theta \in \Theta_0$ vs $H_1: \theta \in \Theta_1$. If Θ_i contains a single element then H_i is simple, otherwise H_i is composite.

Neyman-Pearson Formulation of Hypothesis Testing: Fix $\alpha \in (0, 1)$, the significance level. Require that $P_0(\text{reject } H_0) \leq \alpha, \forall \theta \in \Theta_0$ (α is upper bound on prob. of type I error). Test that satisfy this are Level- α Tests.

A TEST is a function $\phi: X \rightarrow [0, 1]$ interpreted as: if x is observed, then H_0 is rejected with prob $\phi(x)$. Now, $P_0(\text{reject } H_0) = E_{\theta} \phi(X)$. the size of a test ϕ is: $\sup_{\theta \in \Theta_0} E_{\theta} \phi(x)$. A test is level $\alpha \Leftrightarrow$ size $\leq \alpha$.

The power function of a test ϕ is the function $w: \Theta \rightarrow [0, 1]$, defined by $w(\theta) = P_{\theta}(\text{reject } H_0) = E_{\theta} \phi(x)$

The power of a test is $w(\theta)$, where $\theta \in \Theta_1$. [A good test. is one which makes $w(\theta)$ as large as possible on Θ_1 , while satisfying $w(\theta) \leq \alpha, \forall \theta \in \Theta_0$].

SIMPLE Hypotheses: $H_0: \theta = \theta_0$ vs $H_1: \theta = \theta_1$. Assume densities $f_i(x) = f(x; \theta_i)$ is the true state of nature.

Define the likelihood ratio $\Lambda(x) = \frac{f_1(x)}{f_0(x)}$, the larger $\Lambda(x)$, the stronger the evidence against H_0 .

A Likelihood ratio test (LRT) of H_0 vs H_1 is a test $\phi(x)$ of the form: $\phi_0(x) = \begin{cases} 1 & f_1(x) > k f_0(x) \Leftrightarrow \Lambda(x) > k \geq 0 \\ \delta(x) & f_1(x) = k f_0(x), \text{ where } \delta(x): X \rightarrow [0, 1] \\ 0 & f_1(x) < k f_0(x) \end{cases}$ The NPL says the test ϕ_0 is the best test of size α . Also, $\delta(x) = \delta_0$. NPL: (a) optimality condition (b) Existence condition (c) Uniqueness condition.

the critical region of a test is the set of $x \in \mathcal{X}$ for which $\phi(x) = 1$. [Reject $H_0 \Leftrightarrow \phi(x) = 1$].

Composite Hypotheses: Def: A test ϕ_0 is Uniformly most Powerful (UMP) iff (1) ϕ_0 is level- α test: $E_{\theta} \phi_0(x) \leq \alpha \quad \forall \theta \in \Theta_0$ AND (2) if ϕ is another level- α test and $\theta \in \Theta_0$: $E_{\theta} \phi_0(x) \geq E_{\theta} \phi(x)$

Def: the family of densities $\mathcal{F} = \{f(x; \theta) : \theta \in \Theta \subseteq \mathbb{R}\}$ is of monotone likelihood ratio (MLR) iff \exists a function $\tau : \mathcal{X} \rightarrow \mathbb{R}$ s.t. $\lambda(x) = f(x; \theta_2) / f(x; \theta_1)$ is a nondecreasing function of $\tau(x)$ for any $\theta_1 \leq \theta_2$.

THEOREM: Suppose that the density of X belongs to a family that has MLR with respect to $\tau(x)$. For testing $H_0: \theta \leq \theta_0$ vs. $H_1: \theta > \theta_0$, the test: $\phi_0(x) = \begin{cases} 1 & \tau(x) > c \\ 0 & \tau(x) \leq c \end{cases}$ [need to randomize in discrete case], is UMP among all test having same or smaller size.

BAYES FACTORS: Posterior Odds = Prior odds \times Bayes Factor $\Leftrightarrow \frac{P(\theta_1 | x)}{P(\theta_2 | x)} = \frac{\pi_1 f_1(x)}{\pi_2 f_2(x)}$, where $f_0(x) = f(x | \theta_0)$; $f_1(x) = f(x | \theta_1)$. BAYES FACTOR $B = f_1(x) / f_0(x)$. USE B to test $H_0: \theta = \theta_0$ vs $H_1: \theta = \theta_1$, reject H_0 iff B is sufficiently smaller than 1.

Tests are of the form: reject H_0 iff $\theta < k \Leftrightarrow$ reject H_0 iff $f_1(x) / f_0(x) > \frac{1}{k} = c$; form of NP test by NPL.

Examples: Test simple hypothesis: $X \sim \text{Exp}(\theta)$, so X has pdf $f(x) = f(x | \theta) = \begin{cases} \theta e^{-\theta x} & x \geq 0 \\ 0 & x < 0 \end{cases}$

Test $H_0: \theta = 1$ vs $H_1: \theta = 2 \Rightarrow \lambda(x) = f_1(x) / f_0(x) = 2e^{-2x} / e^{-x} = 2e^{-x}$. By NPL, the NP test is $\phi(x) = \begin{cases} 1 & 2e^{-x} > k \\ \gamma_0 & 2e^{-x} = k \\ 0 & 2e^{-x} < k \end{cases}$ To determine k , first $\alpha = E_{\theta=1} \phi(x) = \int_0^{\infty} \phi(x) f_0(x) dx = \int_0^{\infty} 1 \cdot e^{-x} dx = 1$, where $\alpha = \int_0^{\infty} e^{-x} dx = 1 - k/2 \Rightarrow k/2 = 1 - \alpha \Rightarrow k = 2(1 - \alpha)$.

Example 4a: $H_0: X \sim P_0$ vs $H_1: X \sim P_1$. $\mathcal{X} = \{1, 2, 3\}$. Distributions are given by: $P_0(x) = \begin{matrix} x=1 & x=2 & x=3 \\ .009 & .001 & 0.99 \\ P_1(x) & .001 & .989 & 0.01 \\ P_2(x) & \frac{1}{9} & .989 & \frac{1}{9} \end{matrix}$

Construct a NP Test with $\alpha = 0.01$. NP: $x=2$, if we reject H_0 when $x=2$, then $P(\text{Type I Error}) = P_0(x=2) = 0.001$. $x=1$, if we reject H_0 when $x=1$, then $P(\text{Type I Error}) = P_0(x=1) = 0.009$.

So, The NP level- α Test is: $\phi(x) = \begin{cases} 1 & \text{if } x=1, 2 \\ 0 & \text{if } x=3 \end{cases}$

If we observe $x=1, 2$, then we reject H_0 at $\alpha = 0.01$.

Exercise 2.4. (1) $\Theta = \{0, 1\}$, $\theta = 0$ component not functioning, $\theta = 1$ component functioning (2) $\mathcal{X} = \{0, 1\}$ $x=0$, warning light off, $x=1$ warning light on (3) $\mathcal{F} = \{P_0, P_1\}$ $P_0 = \text{Bernoulli}(\frac{2}{3})$; $P_1 = \text{Bernoulli}(\frac{1}{4})$

i.e., $P_0(0) = \frac{1}{3}$; $P_0(1) = \frac{2}{3}$. (4) $\mathcal{A} = \{0, 1\}$; $a=0$ don't launch; $a=1$ launch (5) Loss function $L: \mathcal{A} \times \mathcal{A} \rightarrow \mathbb{R}$. $L(0,0) = 0$, $L(0,1) = 10$, $L(1,0) = 5$; $L(1,1) = 0$ (6) Non-randomized decision rules: $d: \mathcal{X} \rightarrow \mathcal{A}$ there are 2 nonrandomized d -rules: $d_1(x) = 1$; $d_2(x) = 0$; $d_3(x) = \begin{cases} 1 & \text{if } x=1 \\ 0 & \text{if } x=0 \end{cases}$; $d_4(x) = \begin{cases} 0 & \text{if } x=1 \\ 1 & \text{if } x=0 \end{cases}$

Risk functions $R_0(0, d_1) = \sum_{x \in \mathcal{X}} L(0, d_1(x)) P_0(x) = L(0, d_1(0)) P_0(0) + L(0, d_1(1)) P_0(1) = 10 \cdot \frac{1}{3} + 10 \cdot \frac{2}{3} = 10$. AND, same for $R_1(1, d_1) = \sum_{x \in \mathcal{X}} L(1, d_1(x)) P_1(x) = L(1, d_1(0)) P_1(0) + L(1, d_1(1)) P_1(1) = 0 \cdot \frac{3}{4} + 0 \cdot \frac{1}{4} = 0$. AND, same for d_2, d_3, d_4 .

the risk set of randomized rules is the parallelogram whose vertices are the above risk points. (convex hull).

For Bayes rule: Suppose $\pi(0) = \psi = 2/5$ and $\pi(1) = 1 - \psi = 3/5$. The Bayes risk of d is: $\frac{2}{5} R(0, d) + \frac{3}{5} R(1, d)$. So lines of the form $\frac{2}{5} R_0 + \frac{3}{5} R_1 = c$ have constant Bayes risk. Then risk point of Bayes is the (rule) for which c is smallest. So, compute all $\frac{2}{5} K(d_0) + \frac{3}{5} K(d_1)$ and choose d that minimizes this.

HW 5. Suppose that $X_1, \dots, X_5 \sim \text{Pois}(\lambda)$: $P\{X_i = r\} = \frac{e^{-\lambda} \lambda^r}{r!}$; for $r = 0, 1, 2, \dots$. Compare the two tests: (a) $Y = X_1 + \dots + X_5$ reject H_0 iff $Y \geq 4$. Note $Y \sim \text{Pois}(5\lambda)$. (b) reject H_0 iff at least two X_i are non zero.

size of (a): $P_{\lambda=1/2}(\text{reject } H_0) = P_{\lambda=1/2}(Y \geq 4) = 1 - P_{\lambda=1/2}(Y \leq 3) = 1 - \text{ppois}(3, 2.5)$. Power of (a): $P_{\lambda=1}(\text{reject } H_0) = P_{\lambda=1}(Y \geq 4) = 1 - P_{\lambda=1}(Y \leq 3) = 1 - \text{ppois}(3, 5)$. size of (b): $P_{\lambda=1/2}(X_i > 0) = 1 - P_{\lambda=1/2}(X_i = 0) = P_{\lambda=1/2}$. Let $Z \sim \text{Bin}(5, P_{\lambda=1/2})$; size = $P(Z > 2) = 1 - P(Z \leq 2) = 1 - \text{pbinom}(2, 5, P_{\lambda=1/2})$. Power of (b): $P_{\lambda=1}(X_i > 0) = 1 - P_{\lambda=1}(X_i = 0) = P_{\lambda=1}$. Then $P(Z > 2) = 1 - P(Z \leq 2) = 1 - \text{pbinom}(2, 5, P_{\lambda=1})$.

If $X_1, \dots, X_n \sim N(\mu, \sigma^2)$ with μ unknown and σ^2 known. Then: $\bar{X} \sim N(\mu, \sigma^2/n)$ & $\frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \sim N(0, 1)$

$X \sim N(\mu, \sigma^2)$. p.d.f $f(x; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$; $T \sim \text{Exp}(\lambda)$ p.d.f. $f(x; \lambda) = \lambda e^{-\lambda x}$ mean = $\frac{1}{\lambda}$

Example 4.1: $X \sim \text{Binomial}(10, \theta)$. $H_0: \theta \leq \frac{1}{2}$ vs $H_1: \theta > \frac{1}{2}$. Reject H_0 iff $X \geq k$. Given α choose k : $P_0(\text{reject } H_0) = P_0(X \geq k)$ is an increasing function of θ ; hence, the size of the test is $P_{\theta=1/2}(X \geq k) = 1 - P_{\theta=1/2}(X \leq k-1) = 1 - \text{pbinom}(k-1, 10, .5)$. Define: $\phi(x) = \begin{cases} 1 & x \geq 9 \\ \lambda & x = 8 \\ 0 & x \leq 7 \end{cases}$ To find λ_0 : we want size = 0.05. \Rightarrow size = $\max_{\theta \leq 1/2} E_{\theta} \phi(x) = 0.05$. $E_{\theta} \phi(x) = P(X=9) + \lambda P(X=8) = 0.05$, solve for $\lambda = 0.7/35$.

test has size 0.05.